## MODELS

STR502


STR504


## ATTACHING/REMOVING THE FRONT

The front is attached to the base-plate using four clamps, two at the top of the front panel and two at the bottom.

When removing the front-panel use a screwdriver (or similar) and push gently to unhook the clamps at the top and bottom of the front panel.


## CONNECTING



## REMOVING THE CORE

The core panel is attached to the base-plate using two hinges. Remove the core panel by pushing the bottom of the core panel upwards, then unhinging the core panel from the base-plate.

When the core has been turned up-
 wards, the terminal blocks designation becomes visible:

Lap-Top Service Tool Infinet connector

To avoid base plate deformation, be careful when tightening the mounting screws.
Note that the enclosed screws are mainly intended for the US and Australian markets.



## Setpoint Adjustment Wheel

A variable resistor wheel is provided to act as a manual setpoint adjustment. To read its value, configure an Analog input. Connect the wheel orange wire to one of the controller's Ana$\log$ IN terminals. The wheel shares its return signal with that of the thermistor.

The following function can be used to read the value of the wheel control on the STR5xx for setpoint adjustment. The function uses the ElecValue of the wheel (potentiometer) to return the setpoint. It works with 5, 10 or 8 volt input types. This function must be located in the controller to which the STR5xx is wired.

The Plain English code for the function is as shown below. In this example, the function object is named SP.

```
Arg 1 STR5xx 'the actual setpoint wheel (pot)
    'input name
Arg 2 Lower 'temperature setpoint
Arg 3 Upper 'temperature setpoint
Arg 4 RefVolt 'the input type (5, 10 or 8 volt)
Numeric Vref, Rref, Rsens, V, MaxOhms, SetPt
MaxOhms = 10.13 'K ohms - Resistance between wheel
    'terminals when it's at the
    'clockwise end value. Adjust this
    'for field variations.
If RefVolt is 5 then
    Vref = 5.115
    Rref = 10
Else
    If RefVolt is 10 then
        Vref = 10
        Rref = 30.1
    Else
        Vref \(=8.192\)
        Rref \(=30.1\)
    Endif
Endif
If STR5xx ElecValue <= 0 then Return Upper
If STR5xx ElecValue >= Vref then Return Lower
\(\mathrm{V}=\) (Vref/STR5xx ElecValue)
Rsens \(=(V\) * 0.2 - Rref - 0.2) / (1 - V)
SetPt = Lower + ((Rsens/MaxOhms) * (Upper - Lower))
SetPt = minimum(maximum(SetPt, Lower), Upper)
Return SetPt
```

For best accuracy, use a multimeter to measure the resistance between the terminals 12 and 13 on the STR5xx when the wheel is pushed all the way to its clockwise end value. Change the value of MaxOhms in the function to agree with your measured value.

Load the function into the controller and wire up the STR5xx Create a voltage input for the wheel - this example calls it Wheel. Create a numeric setpoint such as STR5xxSP. Write a one line program which sets this numeric equal to the result of the function. In this example, the (looping) program line is: STR5xxSP = SP(Wheel, 69, 75,10)

Refer to the function's Plain English code above for a description of the arguments.

## Occupancy button on STR504

The over-ride push button is connected across the temperature sensor. To read the state of the button you must have configured the sensor input as a Temperature Input at the controller. Firmly pressing the button shorts the sensor which renders a temperature reading of above $150^{\circ} \mathrm{F}\left(65.5^{\circ} \mathrm{C}\right)$ at the input.
An occupancy button can be programmed as follows.

```
InitLine:
    RoomOccupied = Off
CheckTemp:
    If STR504_Room_Temp > 320 then
        RoomOccupied = On
        Goto CheckControl
    Endif
    Goto CheckTemp
CheckControl:
    If RoomOccupied then
        If heater_2 = Off then
            heater_2 = On
        Else
            heater_2 = Off
        Endif
    Endif
WaitNormal:
    If STR504_Room_Temp < 300 then
        Goto ClearTrigger
    Goto WaitNormal
ClearTrigger:
    RoomOccupied = Off
    Goto CheckTemp
```

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